



# U.S. ARMY RESEARCH, DEVELOPMENT AND ENGINEERING COMMAND

**Physics-inspired placement of analytics services on  
heterogeneous resources for multisensor fusion**

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## THE TEAM

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Funded as part of ARL DAIS-ITA Initial Program Plan, with additional support by ARL mission funds.



# PROBLEM: DATA VOLUME

Current flood of data is only the beginning:

- Commercial side:  
Explosion in data collected  
(estimate: 44 billion cameras in use by 2020)
- Tactical Side:  
Future battlefields to contain millions of networked devices  
(Internet of Battlefield Things—IoBT)

**Analyzing data from multitude of sensors will be essential to understand future battlefield from situational awareness to global strategy.**



# NEED FOR EDGE COMPUTING

Cloud computing poses difficulty for IoBT:

- Data transmission is costly in terms of time and energy
- Network is likely to be unreliable due to congestion, jamming, damage, etc.
- Centralized infrastructure creates potential points of failure, reducing system robustness.

Edge computing:

- Places hardware for analysis at or near sensors.
- Performs analysis as close to data as possible.
- Curates data to be sent upward, reducing network traffic.
- Reduces latency in responses to changes in device status.



# MODELS OF EDGE COMPUTING

Different models of edge computing:

- Traditional “Edge Computing”:

Analysis performed on-device:

- + Minimal information needs to be transmitted
  - Requires sufficient processing power on-device (higher costs)
  - Data fusion accesses data from multiple sources
- “Fog Computing”:  
Network contains extra computing power, e.g. at network routers
    - + Individual devices can be inexpensive
    - Network routers are potential points of failure
  - **Distributed model:**  
Many or all devices have some routing and computing capability.  
Set of devices act as a distributed computer  
Individual devices still inexpensive, fewer points of failure

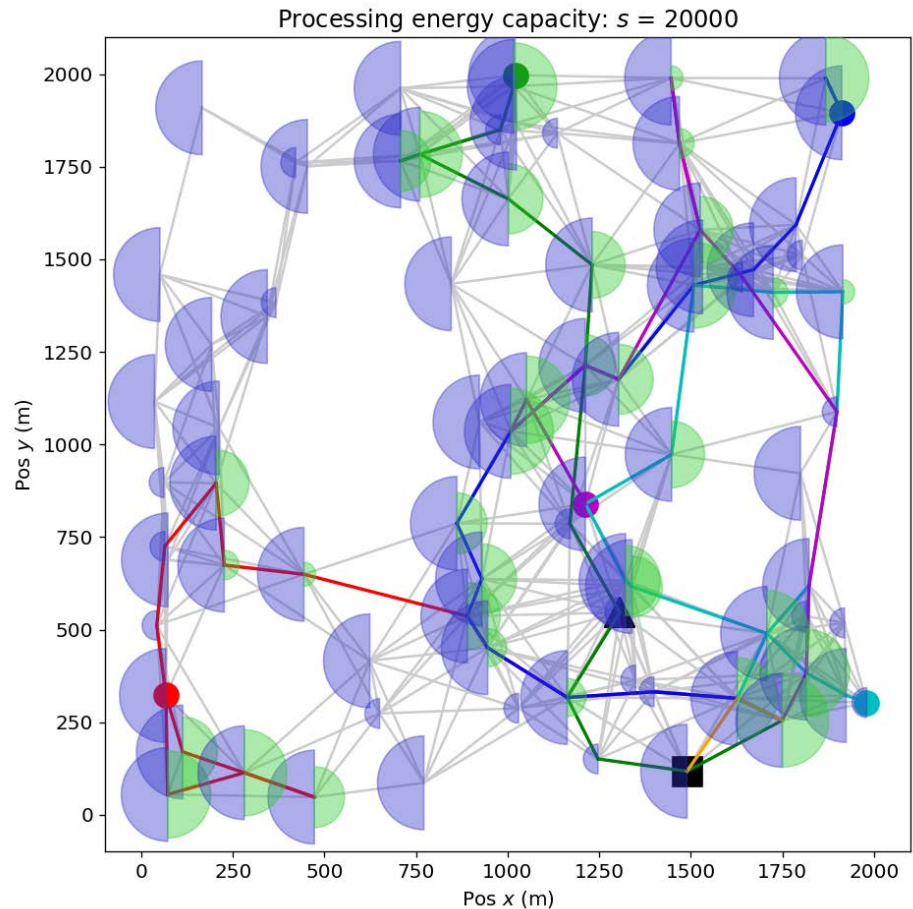


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# TASK: MACHINE-OPTIMIZED COORDINATION OF ANALYTICS DISTRIBUTED ON SENSOR NETWORK

Use the network of devices to create sufficient computing power

- Distributed edge computing model
- Take advantage of each computing device on-network
- Optimization seeks to minimize energy costs, while simultaneously balancing energy usage.
- Handle constraints on available energy, RAM, etc.

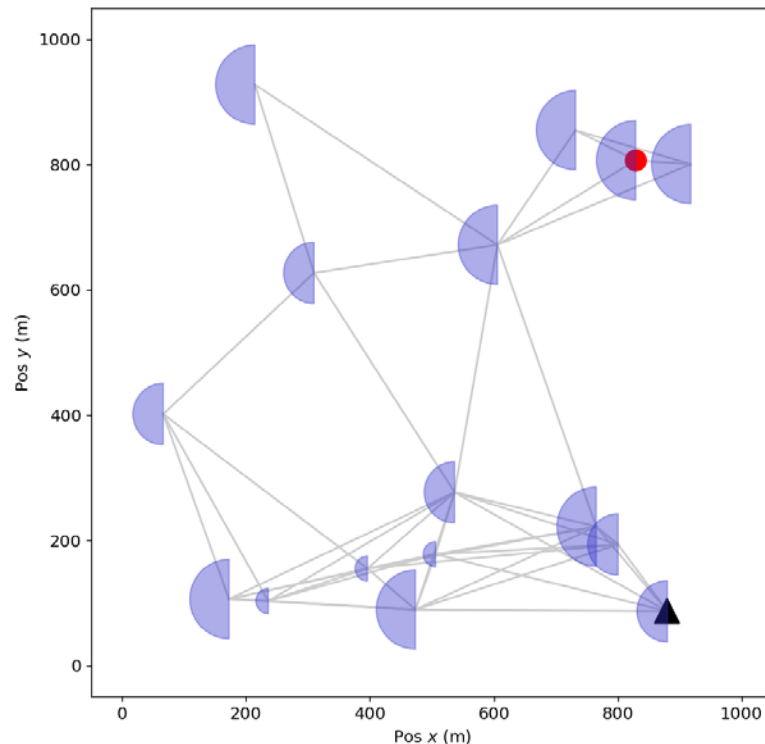




## EXAMPLE: RANDOMLY DISTRIBUTED SENSOR NETWORK

### Example:

- System of networked security cameras/sensors
- Physical nodes occupy geometric random graph on square kilometer.
- Each device consists of:
  - Sensor
  - Cell-phone-class processing/memory
  - Battery
  - Solar Cell
  - Radio (e.g. Wi-Fi) for communications
- Task:
  - Distribute analytics over devices
  - Stay within capacities of devices



16 networked IoT devices on square km with varying capacities. Available communications links based on measured 802.11ac performance.

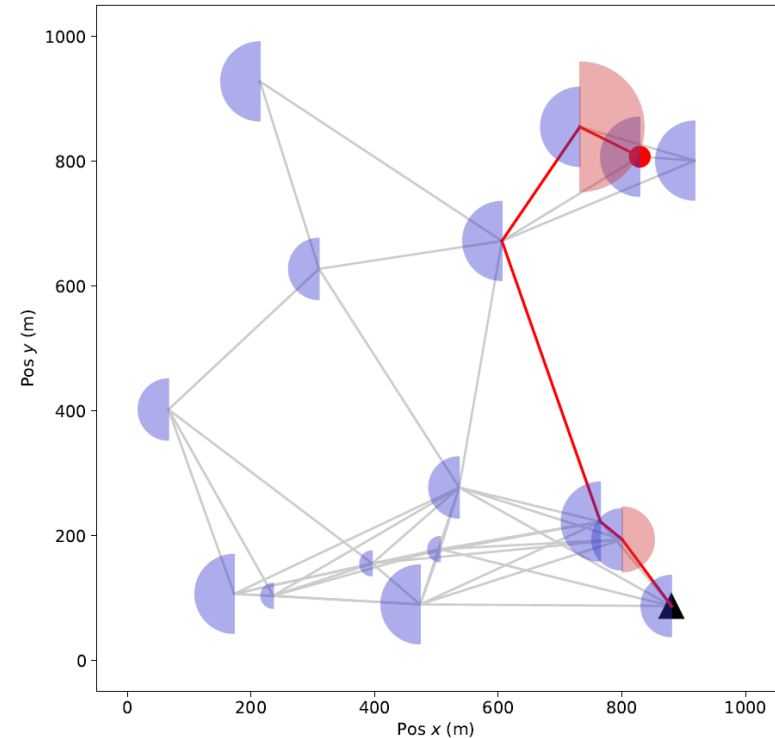


# PROBLEM SET-UP: GRAPH EMBEDDING PROBLEM

Treat as optimal graph embedding problem (OGEB):

- Source (red circle) + observer (black triangle)
- Seek to “optimally” place analytics:
  - Minimize communications
  - Balance load on system
- Seek distributed solution (avoid single points of failure)

**WARNING: OGEP is generally intractable.**



Initial placement of analytics, based on minimum communications path. Blue semicircles for capacity, red semicircles for over-utilization.





# RESOURCES: PHYSICAL GRAPH

Physical graph: Available resources

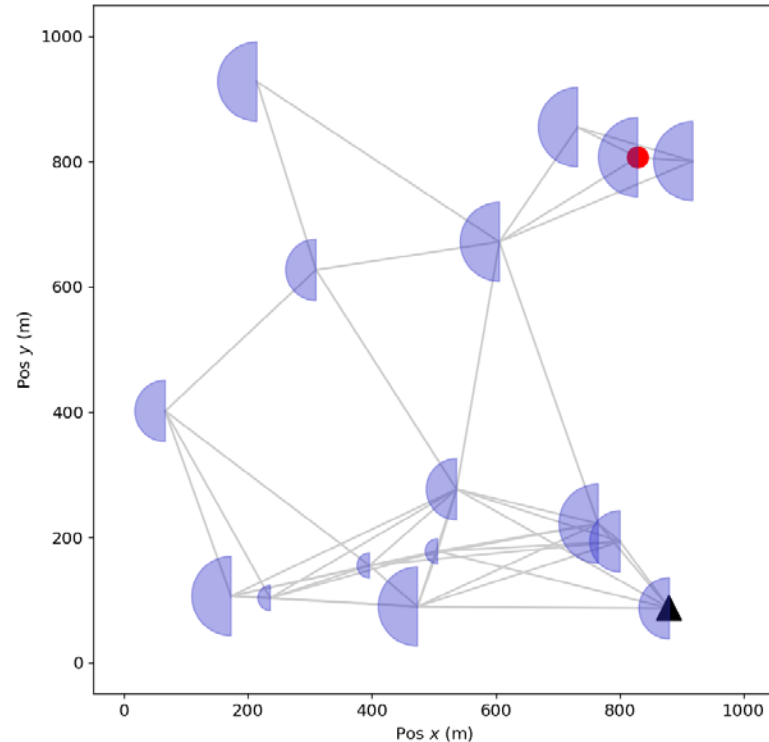
$$\mathcal{H} = (V_P, E_P, Q, R, \omega_P^E)$$

Nodes  
(physical  
devices)

Edges  
(available  
communicati  
ons)

System  
capacities  
(processing  
energy and  
RAM)

Edge  
communi-  
cations  
energy costs



Physical graph composed of networked devices. Connections set by wireless communications. Left-semicircles represent available capacity.



# ANALYTICS: LOGICAL GRAPH

Logical graph: Analytics requirements

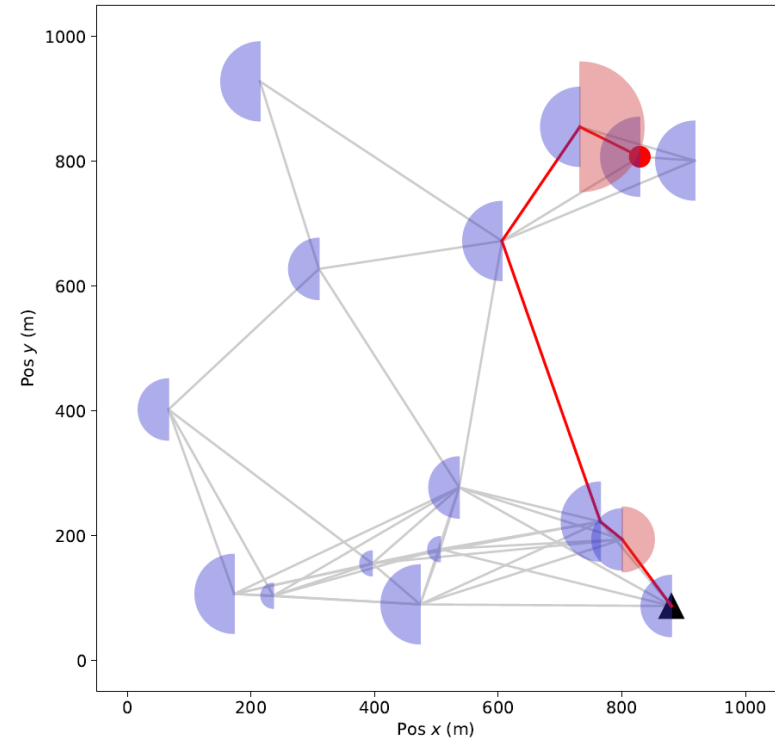
$$\mathcal{G} = (V_A, E_A, q, r, \omega_A^E)$$

Nodes  
(analytics  
stages)

Edges (data  
connections  
between  
nodes)

System  
requirements  
(processing  
energy and  
RAM)

Edge  
communi-  
cations  
requirements



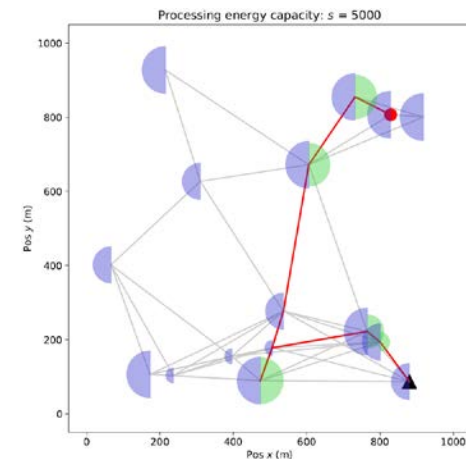
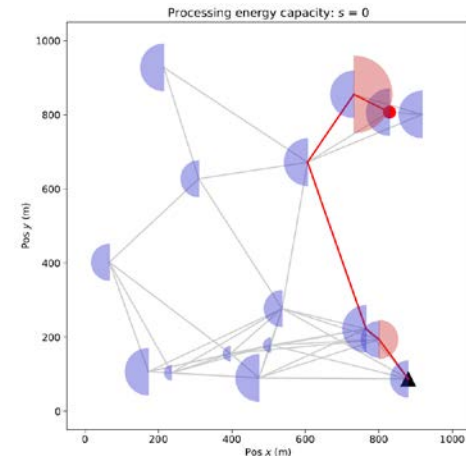
Logical graph: Right semi-circles show system requirements of analytics; heavy red line shows communications path



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# OPTIMIZATION APPROACH: ADAPT DISTRIBUTED MOLECULAR MODELING ALGORITHMS

- Treat nodes of physical and logical graphs particles, similar to particles in molecular simulations.
- Use physics-inspired interactions to obtain objective function.
- Optimize using Metropolis Monte Carlo + Simulated Annealing to find optimal placements.
- Placements are not global optima, but typically quite good and fast.





# OPTIMIZATION PROBLEM: OBJECTIVE FUNCTION 1

Compute placements  $\pi: V_A \rightarrow V_P$ , the mapping of logical nodes to physical nodes, that minimizes

$$\Phi = \Phi_{\text{comms}} + c_{\text{RAM}} \Phi_{\text{RAM}} + c_{\text{proc}} \Phi_{\text{proc}}$$

where  $c_{\text{RAM}}$  and  $c_{\text{proc}}$  are adjustable parameters,

$\Phi_{\text{comms}}$  is actual energy cost of communications,

$$\Phi_{\text{comms}} = E^{\text{comms}},$$

$$E^{\text{comms}} = \sum_{(u,v) \in E_A} \omega_A^E(u,v) \omega_P^E(\pi(u), \pi(v))$$



## OPTIMIZATION PROBLEM: OBJECTIVE FUNCTION 2

$\Phi_{\text{RAM}}$  is a penalty function (soft constraint) to ensure RAM capacity is not exceeded

$$\Phi_{\text{RAM}} = \sum_{z \in V_P} \mathbb{1} \left\{ R_z + \sum_{u \in V_A} r_u \mathbb{1} \{ \pi(u) = z \} > 0 \right\}$$

and  $\Phi_{\text{proc}}$  is a physics-inspired, Coulomb-like potential

$$\Phi_{\text{proc}} = \sum_{z \in V_P} \sum_{u \in V_A} Q_z q_u f(z, \pi(u)) + \sum_{(u,v) \in V_A \times V_A} q_u q_v f(\pi(u), \pi(v))$$

$\Phi_{\text{proc}}$  serves dual role:

- Acts as soft constraint on processing energy limits.
- Balances utilization.



# OPTIMIZATION ALGORITHM: METROPOLIS MONTE CARLO + SIMULATED ANNEALING

## Algorithm:

### Init:

1. Set physical graph
2. Embed logical graph
3. Set cooling schedule  $\tau(s)$
4. Compute initial  $\Phi$

### Iterate for $s=1$ to $s_{\max}$ :

1. Trial move (randomly move one node of logical graph)
2. Compute  $\Delta\Phi$ .
3. If  $\Delta\Phi < 0$  : Accept trial move
4. Else if  $e^{-\Delta\Phi/\tau(s)} > \text{rand}(0, 1)$   
Accept trial move
5. Else: Reject trial move

### Comments:

- $\Phi$  is additive, so only  $\Delta\Phi$  needs to be computed.
- $\Delta\Phi$  can be computed at any physical node with only local information of other nodes
- Parameters  $c_{\text{RAM}}$  and  $c_{\text{proc}}$  and  $\tau(s)$  depend on physical and logical graph—can be preset.



# BALANCED UTILIZATION INDEX

Local final capacity given by

initial capacity (“negative charge”) + utilization (“positive charge”)

$$\bar{Q}_z = Q_z + \sum_{u \in V_A} q_u \mathbb{1} \{ \pi(u) = z \}$$

Use shift to ensure quantities are non-negative

$$Q'_z = \bar{Q}_z - Q_{\min}$$

Balanced Utilization Index (modification of Jain’s fairness index) measures balance of final capacity:

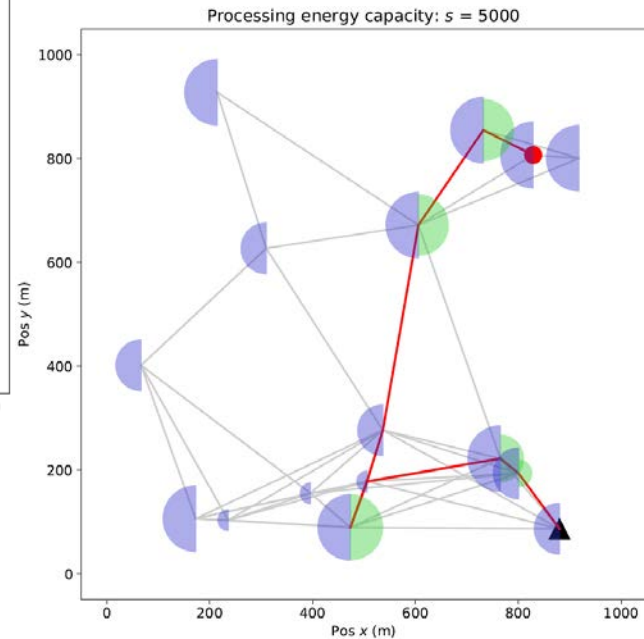
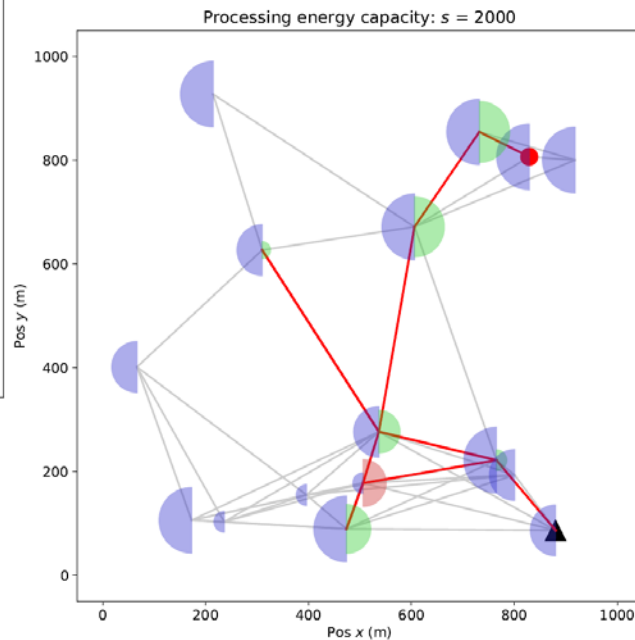
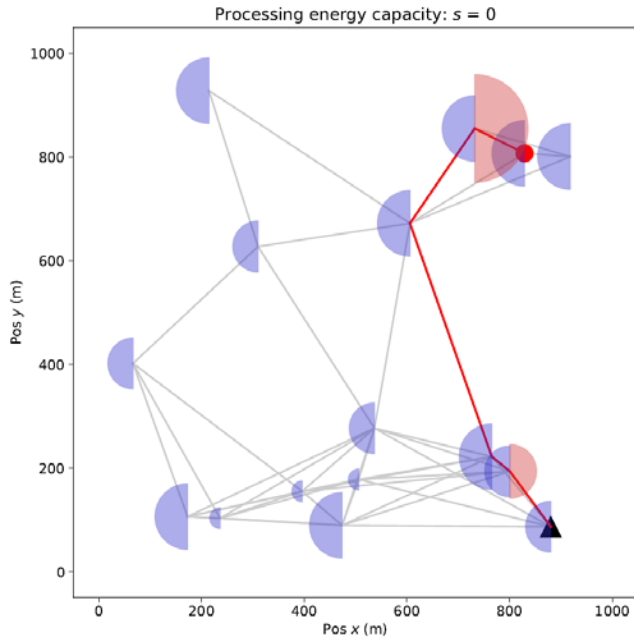
$$I_{BU} = \frac{(\sum_{z=1}^n Q'_z)^2}{n \cdot \sum_{z=1}^n (Q'_z)^2}$$



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# DEMONSTRATION: EVOLUTION OF PLACEMENT SOLUTION

## Processing energy capacity + utilization



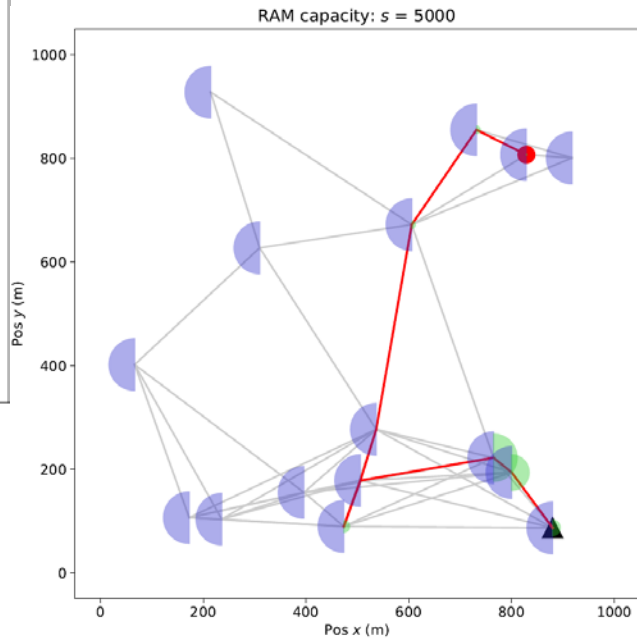
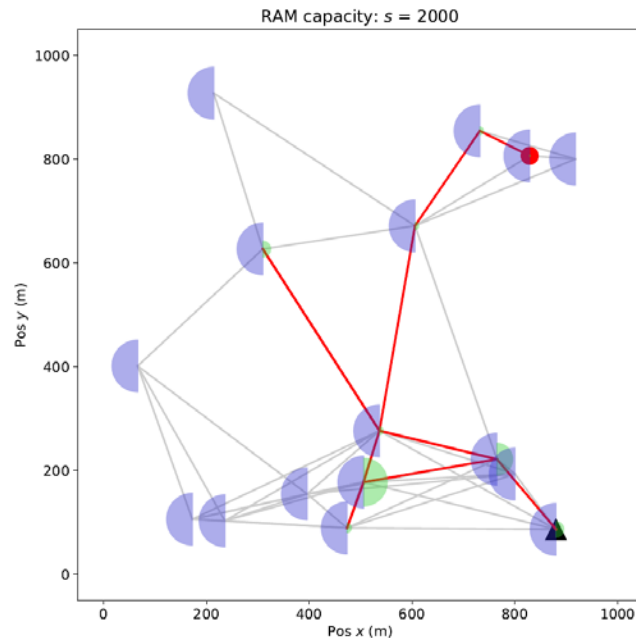
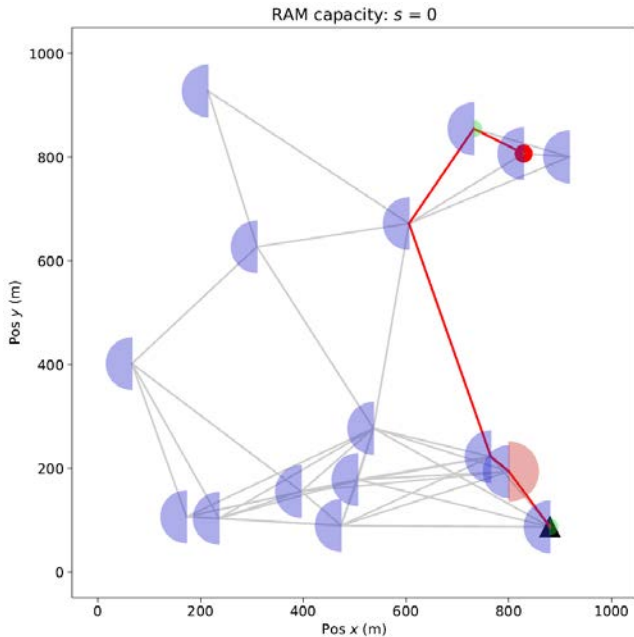
- Only final configuration is important.
- Intermediate configurations show evolution of optimization solution.





# DEMONSTRATION: EVOLUTION OF PLACEMENT SOLUTION

## RAM capacity + utilization



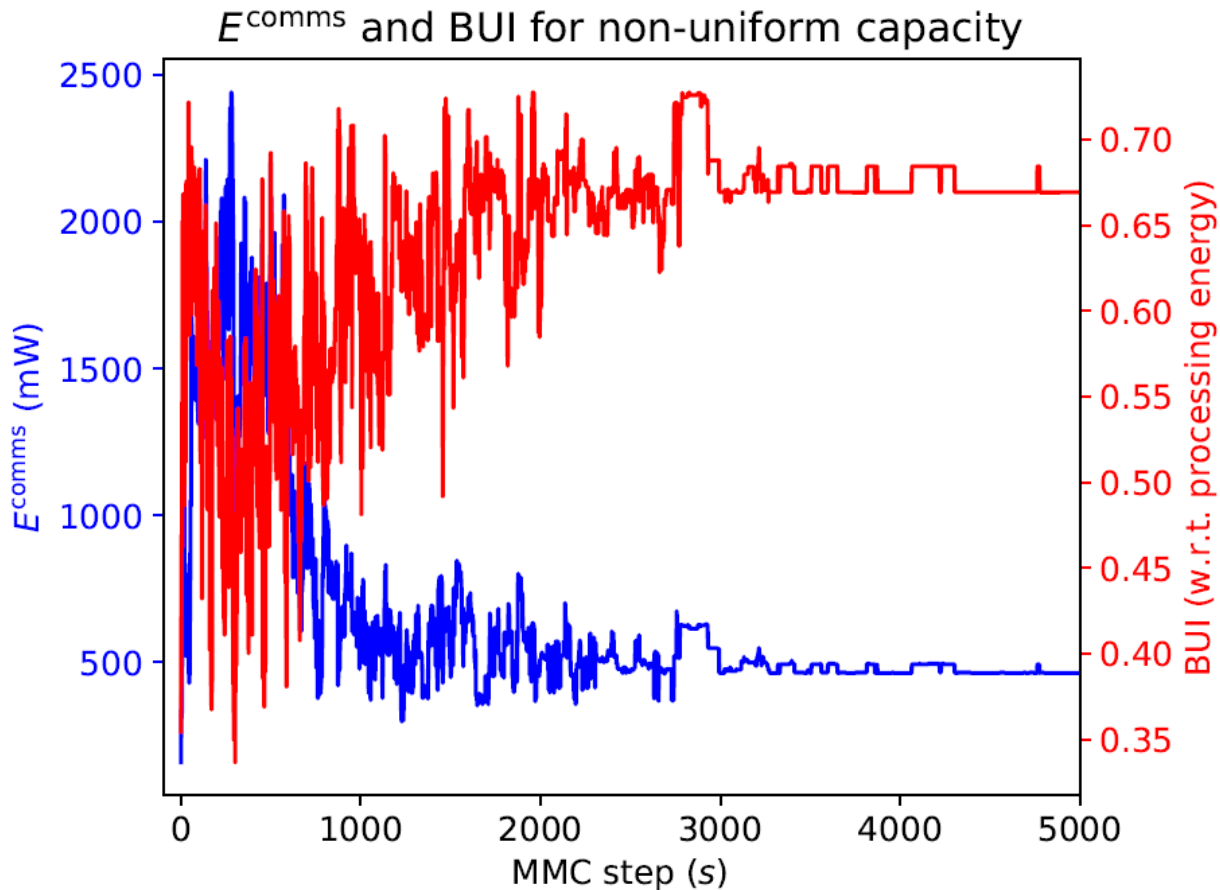
- RAM capacity constraint is robust:  
Satisfied in all calculations in this work



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# DEMONSTRATION: EVOLUTION OF ANALYTICS PLACEMENT

Evolution of  $E_{\text{comms}}$  and BUI:



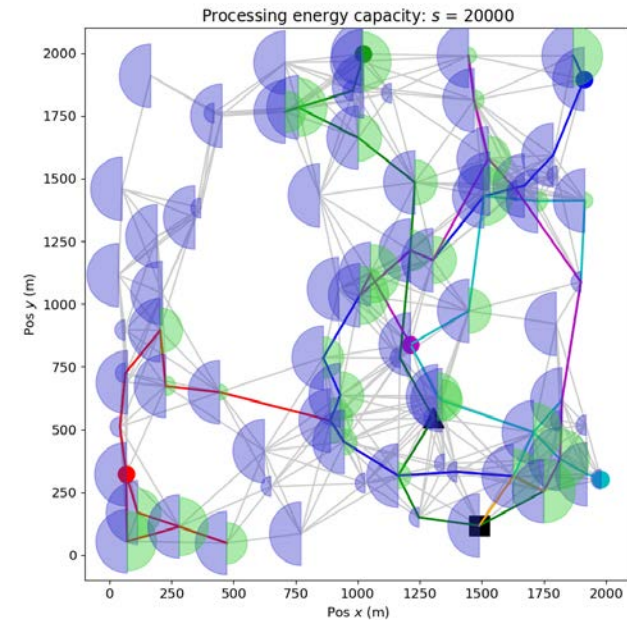
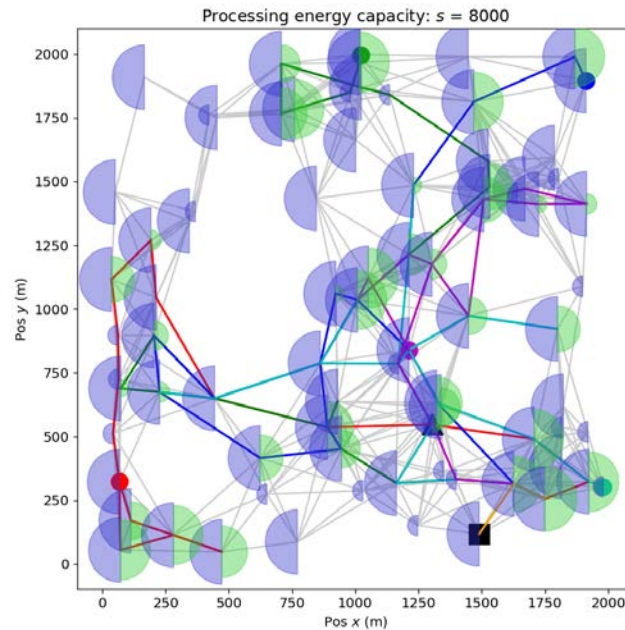
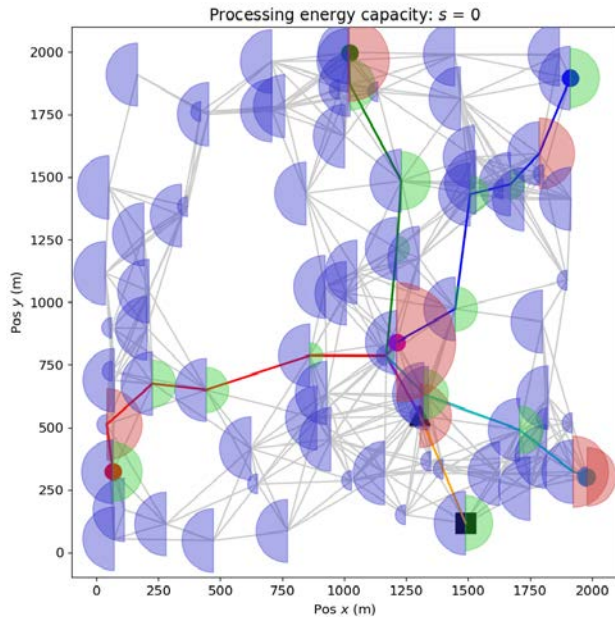
Algorithm is simultaneously optimizing  $E_{\text{comms}}$  and BUI (minimizing and maximizing, respectively).



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# PLACEMENTS FOR MULTISENSOR FUSION PROBLEM

Data from 5 sensors, joined at triangle; fusion completed at square:

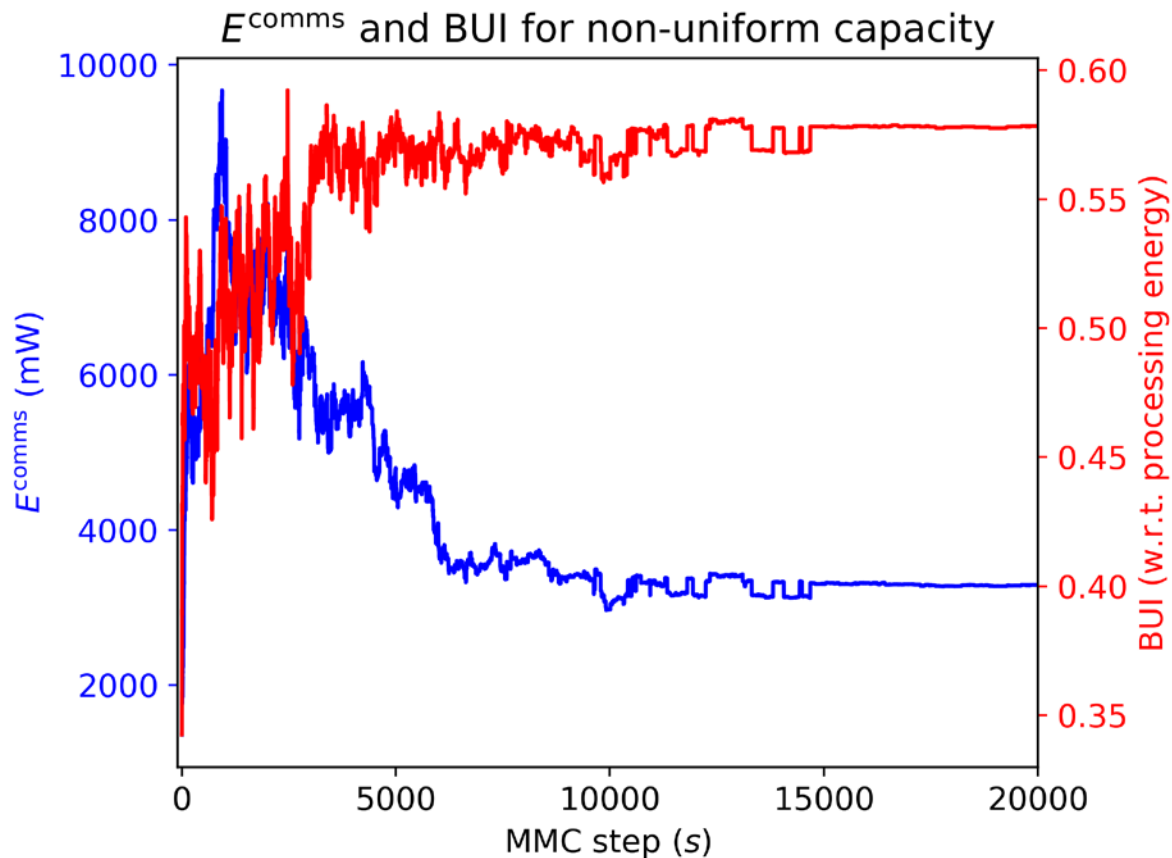




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# MULTISENSOR FUSION: EVOLUTION OF METRICS VS. MMC STEP

Evolution of  $E_{\text{comms}}$  and BUI:



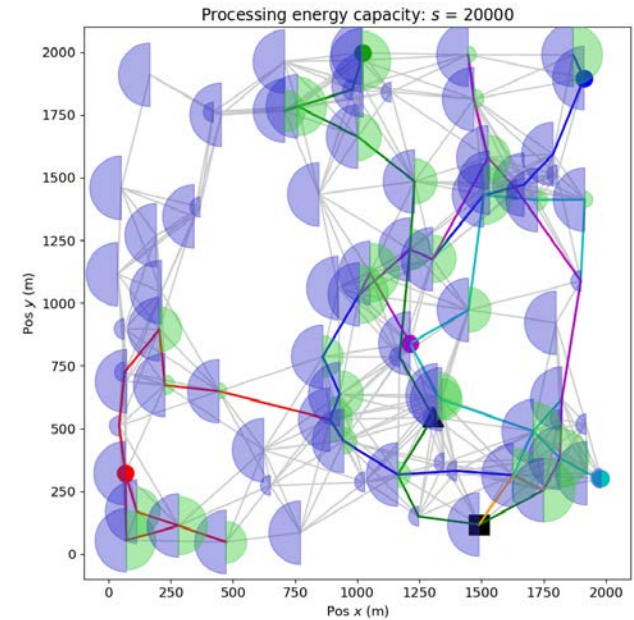
Algorithm is simultaneously optimizing  $E_{\text{comms}}$  and BUI (minimizing and maximizing, respectively).



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# CONCLUSIONS

- Multisensor fusion will be essential to analyzing incoming flood of data.
- On tactical networks, distributed edge computing has potential to replace distant, cloud-based analysis.
- Placement problem for components of distributed computation can be abstracted as optimal graph embedding problem (OGEP).
- Objective function defined in terms of physics-inspired interactions.
- Metropolis Monte Carlo-Simulated Annealing can find optimal placements that balance utilization while minimizing energy costs.



More details: Kraczek et al., *SPIE Proceedings: Disruptive Technologies in Information Sciences*, **10652** (2018); related work submitted to INFOCOM.